

Time series outlier detection using penalised regression

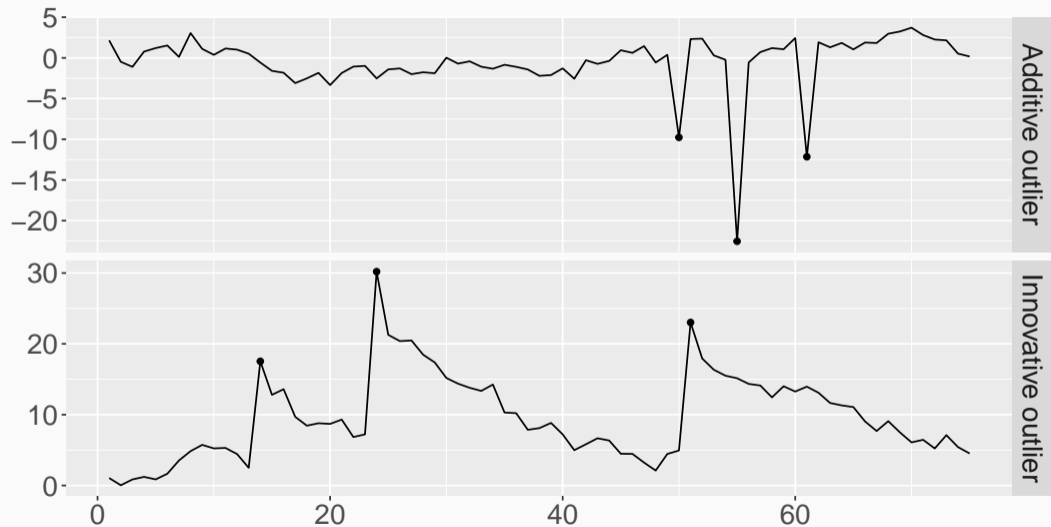
Yangzhuoran Fin Yang
Ines Wilms
Jakob Raymaekers



Maastricht University
School of Business and Economics



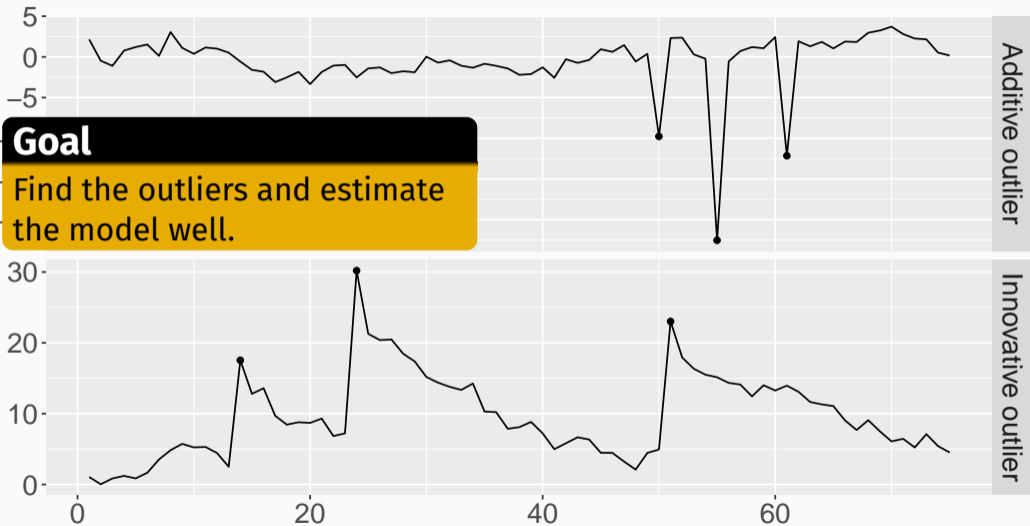
Outliers in time series



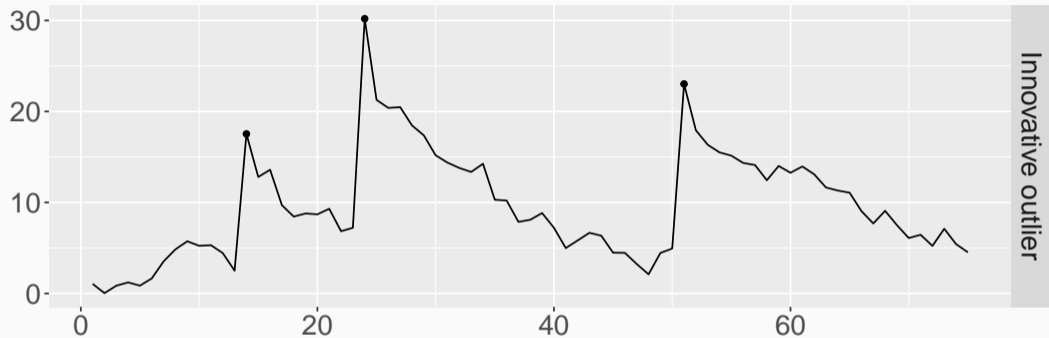
Outliers in time series

Goal

Find the outliers and estimate the model well.



Innovative outlier



Innovative outlier

$$y_t = \gamma_t + \varphi_1 y_{t-1} + \dots + \varphi_p y_{t-p} + \varepsilon_t$$

IPOD for Innovative Outliers

Thresholding based Iterative Procedure for Outlier Detection
(She and Owen 2011)

Innovative outliers

$$y_t = \gamma_t + \varphi_1 y_{t-1} + \cdots + \varphi_p y_{t-p} + \varepsilon_t$$

IPOD Objective function

$$\min_{\gamma} f_{\text{soft}}(\varphi, \gamma; \lambda) = \frac{1}{2} \|\mathbf{y} - \mathbf{Y}\varphi - \gamma\|_2^2 + \sum_{t=1}^T \lambda_t |\gamma_t|.$$

IPOD for Innovative Outliers

Objective function

$$\min_{\gamma} f_{\text{soft}}(\varphi, \gamma; \lambda) = \frac{1}{2} \|\mathbf{y} - \mathbf{Y}\varphi - \gamma\|_2^2 + \sum_{t=1}^T \lambda_t |\gamma_t|$$

$$\mathbf{y} = [y_1, y_2, \dots, y_T]'$$
$$\mathbf{Y} = \begin{bmatrix} y_0 & y_{-1} & \cdots & y_{-p+1} \\ y_1 & y_0 & \cdots & y_{-p+2} \\ \vdots & \ddots & & \vdots \\ y_{T-1} & y_{T-2} & \cdots & y_{T-p} \end{bmatrix}$$

IPOD for Innovative Outliers

Objective function

$$\min_{\gamma} f_{\text{soft}}(\varphi, \gamma; \lambda) = \frac{1}{2} \|\mathbf{y} - \mathbf{Y}\varphi - \gamma\|_2^2 + \sum_{t=1}^T \lambda_t |\gamma_t|$$

Jointly convex in φ and γ - Alternating optimisation

IPOD for Innovative Outliers

Objective function

$$\min_{\gamma} f_{\text{soft}}(\varphi, \gamma; \lambda) = \frac{1}{2} \|\mathbf{y} - \mathbf{Y}\varphi - \gamma\|_2^2 + \sum_{t=1}^T \lambda_t |\gamma_t|$$

Jointly convex in φ and γ - Alternating optimisation

IPOD

while not converged do

- 1 Estimate φ
- 2 Thresholding $(\mathbf{y} - \mathbf{Y}\hat{\varphi})$ to obtain optimal γ

end while

Proximal gradient descent

IPOD

while not converged do

- 1 Estimate φ
- 2 Thresholding ($\mathbf{y} - \mathbf{Y}\hat{\varphi}$) to obtain optimal γ

end while

Thresholding

$$r_t = \mathbf{y}_t - \varphi \mathbf{y}_{t-1} \quad \Theta_{\text{soft}}(r; \lambda) = \begin{cases} r - \lambda & r > \lambda \\ 0 & -\lambda \leq r \leq \lambda \\ r + \lambda & r < -\lambda \end{cases}$$

Proximal gradient descent

IPOD

while not converged do

- 1 Estimate φ
- 2 Thresholding ($\mathbf{y} - \mathbf{Y}\hat{\varphi}$) to obtain optimal γ

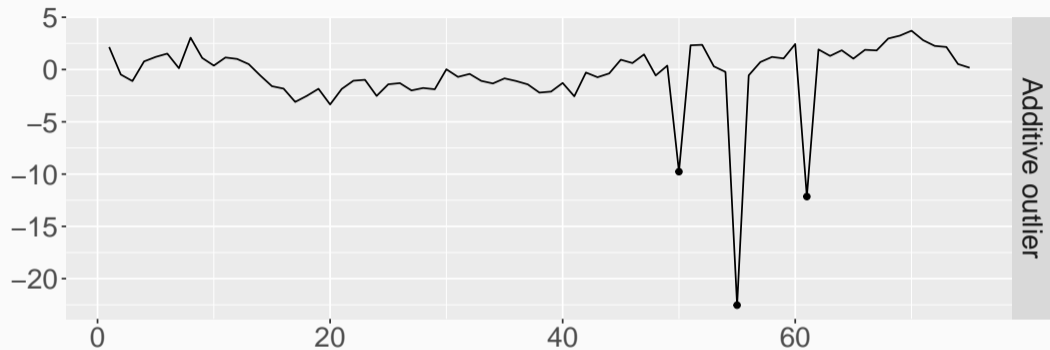
end while

Thresholding

Same for cross-sectional data

$$r_t = y_t - \varphi y_{t-1} \quad \Theta_{\text{soft}}(r; \lambda) = \begin{cases} r - \lambda & r > \lambda \\ 0 & -\lambda \leq r \leq \lambda \\ r + \lambda & r < -\lambda \end{cases}$$

Additive outlier



Additive outlier

$$y_t = \gamma_t + u_t$$

$$u_t = \varphi_1 u_{t-1} + \varphi_2 u_{t-2} + \dots + \varphi_p u_{t-p} + \varepsilon_t$$

IPOD for Additive Outliers?

Additive outliers

$$y_t = \gamma_t + u_t$$

$$u_t = \varphi_1 u_{t-1} + \varphi_2 u_{t-2} + \cdots + \varphi_p u_{t-p} + \varepsilon_t$$

IPOD Objective function

$$\min_{\gamma} f_{\text{soft}}(\varphi, \gamma; \lambda) = \frac{1}{2} \|\mathbf{y} - \mathbf{U}\varphi - \gamma\|_2^2 + \sum_{t=1}^T \lambda_t |\gamma_t|.$$

IPOD for Additive Outliers?

Objective function

$$\min_{\gamma} f_{\text{soft}}(\varphi, \gamma; \lambda) = \frac{1}{2} \|\mathbf{y} - \mathbf{U}\varphi - \gamma\|_2^2 + \sum_{t=1}^T \lambda_t |\gamma_t|$$

IPOD?

while not converged do

- 1 Estimate φ
- 2 Thresholding $(\mathbf{y} - \mathbf{U}\hat{\varphi})$ to obtain optimal γ

end while

Proximal gradient descent?

IPOD?

while not converged do

- 1 Estimate φ
- 2 Thresholding ($\mathbf{y} - \mathbf{U}\hat{\varphi}$) to obtain optimal γ

end while

Thresholding

$$r = \mathbf{y} - \hat{\mathbf{u}} \quad \Theta_{\text{soft}}(r; \lambda) = \begin{cases} r - \lambda & r > \lambda \\ 0 & -\lambda \leq r \leq \lambda \\ r + \lambda & r < -\lambda \end{cases}$$

Proximal gradient descent?

IPOD?

while not converged do

- 1 Estimate φ
- 2 Thresholding ($\mathbf{y} - \mathbf{U}\hat{\varphi}$) to obtain optimal γ

end while

Thresholding

No longer solves a consistent objective function!

$$r = y - \hat{u} \quad \Theta_{\text{soft}}(r; \lambda) = \begin{cases} 0 & -\lambda \leq r \leq \lambda \\ r + \lambda & r < -\lambda \\ r - \lambda & r > \lambda \end{cases}$$

Solving it properly

After some derivation...

For given φ , solving for γ can be expressed as a lasso problem.

$$\min_{\gamma} f_{\text{soft}}(\gamma; \lambda, \varphi) = \frac{1}{2} \|\Phi^* \gamma - \delta\|_2^2 + \sum_{t=1}^T \lambda_t |\gamma_t|$$

```
while not converged do
```

```
  1 Estimate  $\varphi$ 
```

```
  2 Inner proximal gradient descent loop
```

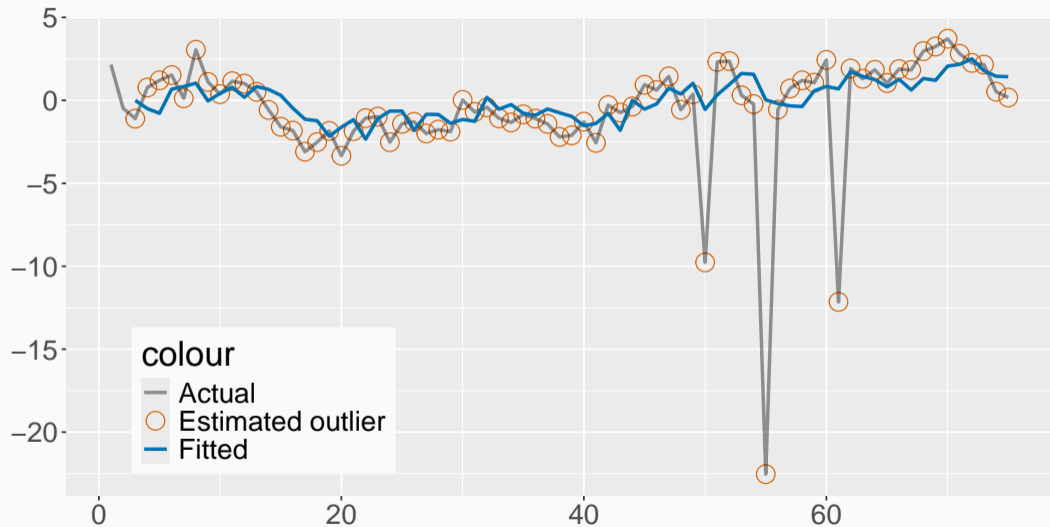
```
    ▶ while not converged do
```

```
      Thresholding to obtain optimal  $\gamma$ 
```

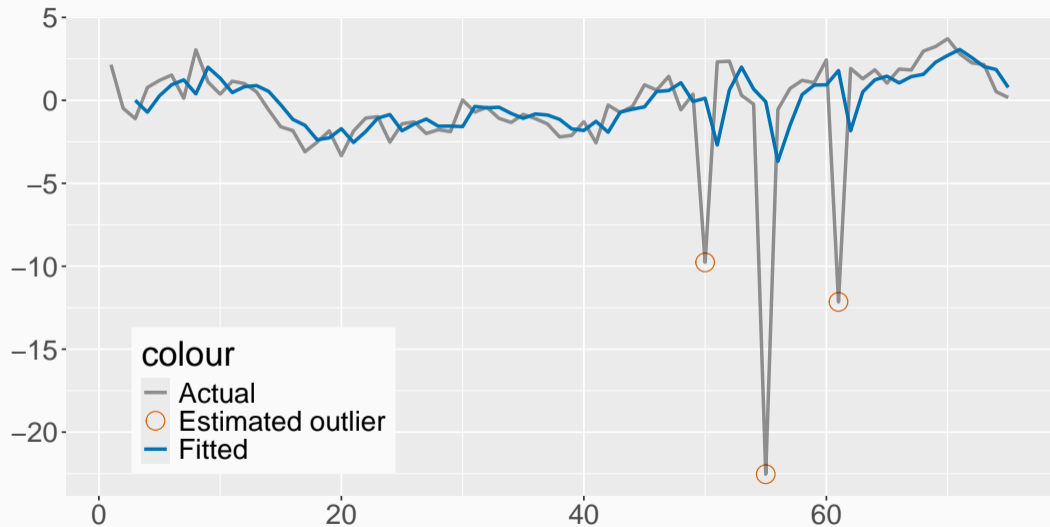
```
    end while
```

```
end while
```

Optimisation: Iteration 0



Optimisation: Iteration 1



Observation

Outliers can be identified

Observation

Outliers can be identified but **underestimated**.

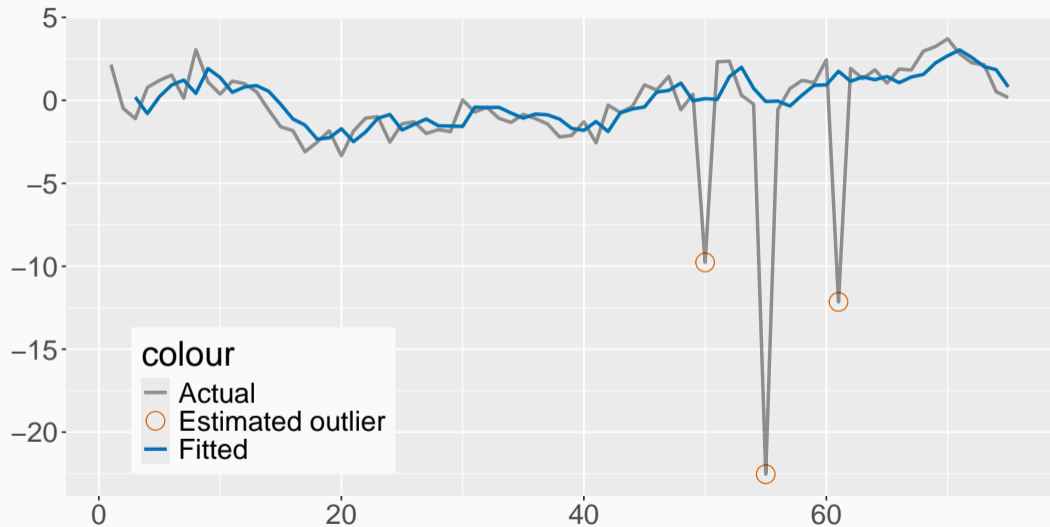
Observation

Outliers can be identified but **underestimated**.

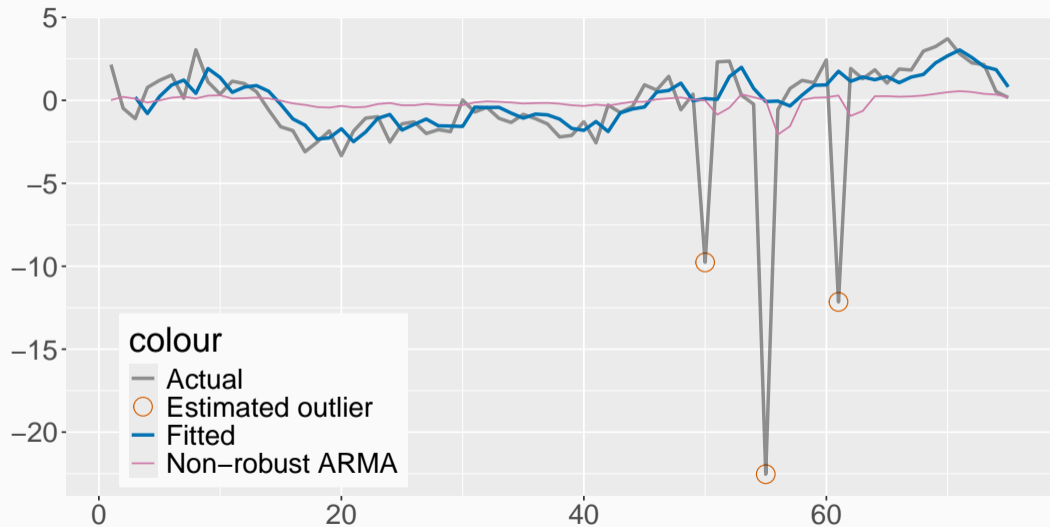
Reweighting

- 1 Remove the effects of estimated outlier and refit the model
- 2 Keep $(\mathbf{y} - \mathbf{U}\hat{\boldsymbol{\varphi}})$ at the locations of the identified outlier as the new estimated outliers
- 3 Refit the model with the effects of the new outliers removed

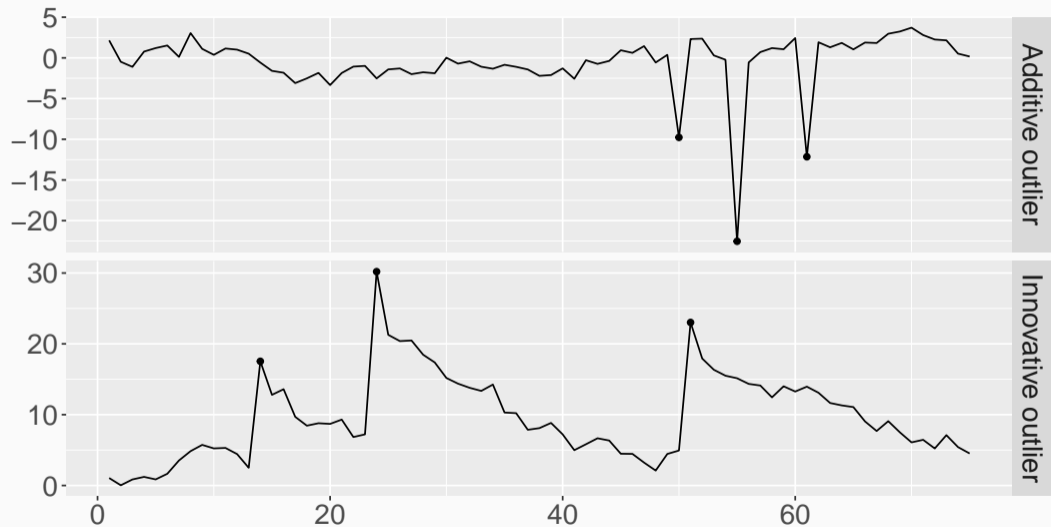
Iteration... and Reweight



Non-robust ARMA



Outliers in time series



AR(1): First obs is an outlier

Objective function

$$\min \sum_{t=2}^T \tilde{e}_t^2$$

$$\tilde{e}_2 = y_2 - \gamma_2 - \varphi(y_1 - \gamma_1) = y_2 - \varphi(y_1 - \gamma_1) = e_2 + \varphi\gamma_1$$

$$\tilde{e}_3 = y_3 - \gamma_3 - \varphi(y_2 - \gamma_2) = y_3 - \varphi y_2 = e_3$$

$$\tilde{e}_t = e_t, \text{ where } e_t = y_t - \varphi y_{t-1}$$

Optimal γ

$$\gamma_1^* = \frac{e_2}{\varphi}$$

AR(1): First two obs are outliers

Objective function

$$\min \sum_{t=2}^T \tilde{e}_t^2$$

$$\tilde{e}_2 = y_2 - \gamma_2 - \varphi(y_1 - \gamma_1) = y_2 - \gamma_2 - \varphi(e_1 - \gamma_1) = e_2 + \varphi\gamma_1 - \gamma_2$$

$$\tilde{e}_3 = y_3 - \gamma_3 - \varphi(y_2 - \gamma_2) = y_3 - \varphi(y_2 - \gamma_2) = e_3 + \varphi\gamma_2$$

$$\tilde{e}_t = e_t$$

Optimal γ

$$\gamma_2^* = -\frac{e_3}{\varphi} = -\frac{y_3 - \varphi y_2}{\varphi} \quad \gamma_1^* = -\frac{e_2 - \gamma_2^*}{\varphi} = -\frac{e_2}{\varphi} - \frac{e_3}{\varphi^2}$$

AR(1): First two obs are outliers

Objective function

$$\min \sum_{t=2}^T \tilde{e}_t^2$$

$$\tilde{e}_2 = y_2 - \gamma_2 - \varphi(y_1 - \gamma_1) = y_2 - \gamma_2 - \varphi(e_1 - \gamma_1) = e_2 + \varphi\gamma_1 - \gamma_2$$

$$\tilde{e}_3 = y_3 - \gamma_3 - \varphi(y_2 - \gamma_2) = y_3 - \varphi(y_2 - \gamma_2) = e_3 + \varphi\gamma_2$$

Optimal value of γ_i depends on optimal value of γ_j

Optimal γ

$$\gamma_2^* = -\frac{e_3}{\varphi} = -\frac{y_3 - \varphi y_2}{\varphi} \quad \gamma_1^* = -\frac{e_2 - \gamma_2^*}{\varphi} = -\frac{e_2}{\varphi} - \frac{e_3}{\varphi^2}$$

AR(1): First two obs are outliers

Objective function

$$\min \sum_{t=2}^T \tilde{e}_t^2$$

$$\tilde{e}_2 = y_2 - \gamma_2 - \varphi(y_1 - \gamma_1) = y_2 - \gamma_2 - \varphi(e_1 - \gamma_1) = e_2 + \varphi\gamma_1 - \gamma_2$$

$$\tilde{e}_3 = y_3 - \gamma_3 - \varphi(y_2 - \gamma_2) = y_3 - \varphi(y_2 - \gamma_2) = e_3 + \varphi\gamma_2$$

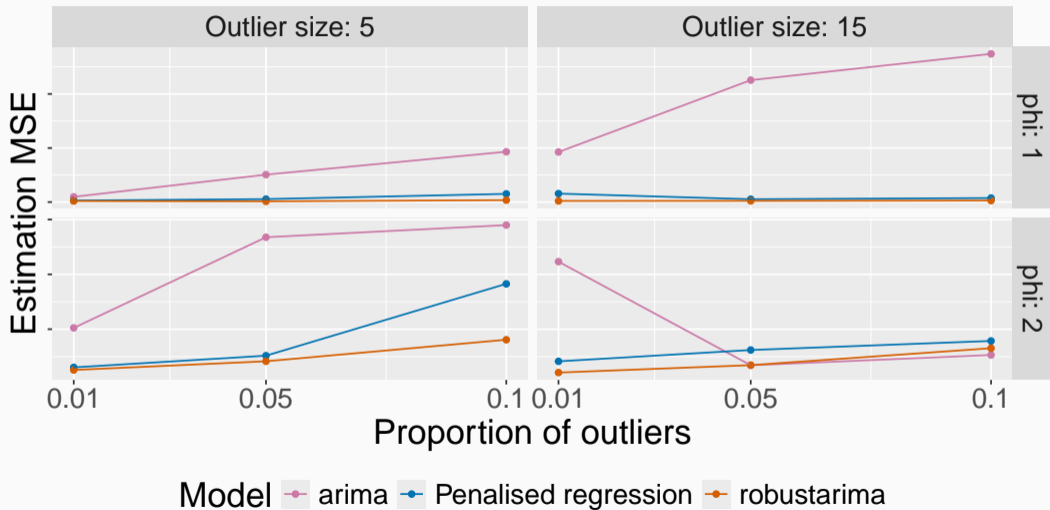
Optimal value of γ_i depends on optimal value of γ_j

Optimal γ

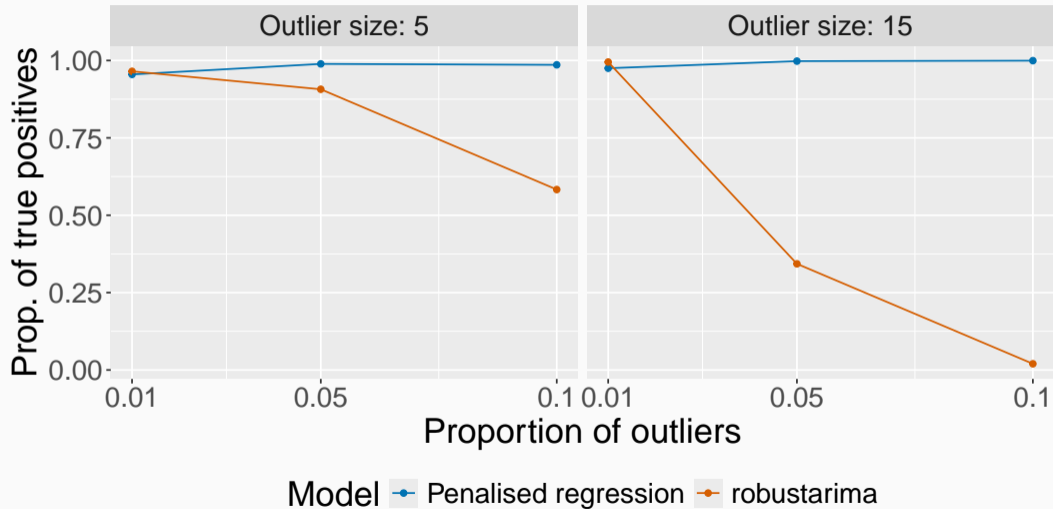
$$\gamma_2^* = -\frac{e_3}{\varphi} = -\frac{y_3}{\varphi}$$

Never the case for innovative outliers!

Performance: Model estimation (no reweight)



Performance: Outlier identification





Contact



Slides:

[yangzhuoranyang.com/
talk/isf-2026](http://yangzhuoranyang.com/talk/isf-2026)

 yangzhuoranyang.com

 [yangzhuoran.yang
@maastrichtuniversity.nl](mailto:yangzhuoran.yang@maastrichtuniversity.nl)

References

She, Yiyuan, and Art B Owen. 2011. "Outlier detection using nonconvex penalized regression." *J. Am. Stat. Assoc.* 106 (494): 626–39. <https://doi.org/10.1198/jasa.2011.tm10390>.